

COMPUTER SIMULATION HISTORY

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APPLICATION OF THE METHOD BELLMAN DYNAMIC PROGRAMMING FOR THE IMPLEMENTATION OF HIGH-RELIABLE PROCESSING SYSTEMS ELECTRONIC MEDICAL DATA

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Abstract

The aim of the work is to analyze the possibilities of applying the Bellman dynamic programming method to create highly reliable (fault-tolerant) systems designed for processing electronic medical data for various purposes. It is shown in the work that the fulfillment of the specified requirements for the reliability of such systems can be ensured by ensuring the redundancy (organization of redundancy) of the system components - both hardware and software. The authors substantiated specific scientific and technical proposals for optimizing and calculating the number of redundant system components (in particular, for the required multiplicity of backup databases that underlie electronic medical data processing systems), allowing to fulfill the established requirements for the reliability of such systems while reducing costs their implementation, as well as relevant examples of calculations. The mathematical apparatus of probability theory and reliability theory, as well as linear programming, in particular, the Bellman dynamic programming method, is used in this work. In addition, the paper presents scientific and technical proposals for the use of the concept of “absolutely reliable” systems that are widely used in reliability theory in organizing highly reliable electronic medical data processing systems. Systems implemented using this approach will ensure that the specified requirements for their reliability are met, while simpler (qualitative) reliability criteria can be used to evaluate them in practice.

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Keywords: electronic medical data processing systems, databases, redundancy of hardware and software components of the system, “absolutely reliable” systems, Bellman dynamic programming.

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[, 2016; , 2017; , 2018].

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Table 1

()
The probability of component failure (databases of various types) and their cost

()	, q_i	C_i
1	0,2	5
2	0,1	4
3	0,15	3

2
Table 2

()
Solution options in the first step (for two databases)

	2=0 0,1/4	2=1 0,01/8	2=2 0,001/12
1=0; 0,2/5	0,3/9	0,21/13	0,201/17
1=1; 0,04/10	0,14/14	0,05/18	0,041/22
1=2; 0,08/15	0,108/19	0,018/23*	0,009/27*

2 :
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, ^1,2;

(), 1,2.
q_{1,2} 1,2 :

$$q_{1,2}^{r+1} = q_1^{r+1} + q_2^{r+1} - q_1^r \cdot q_2^r$$

$$C_{1,2} = C_1(q_1^{r+1}) + C_2(q_2^{r+1})$$

A_1, A_2 - ()

2 ,
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3, :

$$q_{1,2,3}^{r+1} = q_{1,2}^{r+1} + q_3^{r+1} - q_{1,2}^r \cdot q_3^r$$

$$^{\wedge}1,2,3 = ^{\wedge}1,2 + C_3^{\wedge} - C_3^{\wedge} \quad (1)$$

$$r_i=2, \quad 2=1, \quad 3=2,$$

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Table 3

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Solution options in the second step (for three databases)

	2	
	1=2 2=1	1=2 2=2
3=0; 0,15/3	0,018/23	0,009/27
3=1; 0,023/6	0,168/26	0,159/30
3=2; 0,003/9	0,041/29	0,032/33
	0,021/32	0,012/36*

$$q = 0,021.$$

(, ri=0)

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[, 2003]

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[, 2003].

1. () « »
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2. () ; « »
() m
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1. ()

$$= 2 \cdot 10^{-7}$$

(
 0,999; 0,99 0,9).
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([^]) = e^{-λt}.

$$P(t) = e^{-\int_0^t A(t) dt} \quad A(t) = \text{const}$$

$$nAt < -\ln p$$

$$t_p = \frac{-\ln 0,999}{2,10 \cdot 10^{-7} - 50} = 100$$

Henp $\frac{2^{\wedge}}{2,10 \cdot 10^{-7} - 50} = 1000$;

$$t_p = \frac{-\ln 0,999}{2,10 \cdot 10^{-7} - 50} = 1050$$

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2. « »

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$$(\wedge) = q(t_H e^{-p})^m,$$

(1) - ()
 , m-

$$m = \frac{\ln (\wedge)}{\ln q(t_H e^{-p})} - 1,$$

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m
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4.
4
Table 4

« »
The number of backup elements of an absolutely reliable system

		m
0,999		3,292 « 4
		2
		2,641 « 3
0,99		1,861 « 2
		1
		1,427 « 2
0,9		0,431 « 1
		1
		0,214 « 1

1 [2008; 2012;
2018; 2019].

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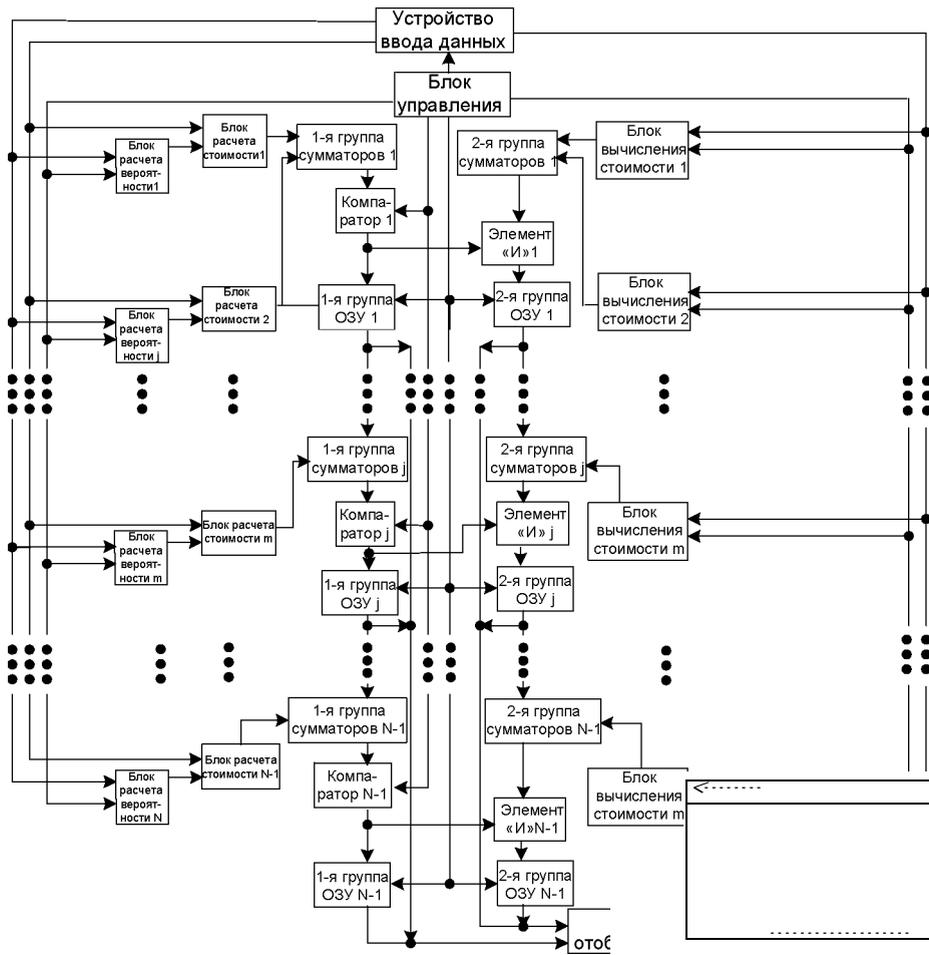
« » [2003].

« »:

() [2003]:

$$\sum_{i=1}^n Z_i = Z - ZP(44) P(4A,A) - \dots + (-1)^{n-1} (, .)$$

i, j, k



. 1.
Fig. 1. Device for solving optimization problems

« ... », [... , 2003; ... 2012; ... , 2019]: ... (...); ... (...) « ... », ... (...) [... , 2018; ... , 2019],

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